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Weekly Report 4 (June 8, 2006)

I'm still trying to figure out how to make my platform pan and tilt. I think that I have came up with a good idea and have ordered servos, gears, and made something out of aluminum to mount it all to. I have also got my lcd to work with my board. It runs a small program that increments a number.

I plan on connecting my CMU Cam to my board tomorrow and will try to communicate with it via the uart on the mavrick board.

Although the TA's are helpful and trying to find a solution, they still don't know how to cut out anything that has been designed using ProE. There are also no copies of autocad for us to use.